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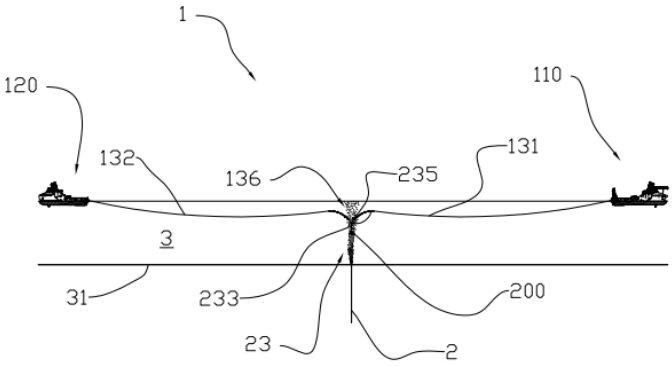
(54) Title **Multi vessel method and system for placing an object on a seabed**

(56) References Cited: US 2015/308210 A1, WO 2016/033278 A1, US 4324505 A, US 2013/118754 A1, WO 2010/144187 A1, US 2012/275274 A1

(57) Abstract

Described herein is a method for placing an object (200) on a seabed (31), the method comprising the steps of: connecting the object (200) to at least two vessels (110, 120) by use of a work wire (131, 132); and co-operating the vessels (110, 120) to move the object (200) into a position in a sea (3) distant from the vessels (110, 120), to lower the object (200) to the seabed (31) and to place the object (200) on the seabed (31), and a system (1) for transporting an object (200) to a position in a sea (3) where the water comprises gas bubbles (23) significantly lowering the load-carrying capacity of the water and for lowering the object to an area on a seabed (31) having a wellbore (2) from which the gas bubbles (23) enter the sea (3).



MULTI VESSEL METHOD AND SYSTEM FOR PLACING AN OBJECT ON A SEABED

Field of invention

The present invention relates to the field of subsea-well technology, and in particular to subsea-well emergency response. The invention more particularly relates to containment of a well, to stop an uncontrolled release of hydrocarbons comprising a release of gas. However, the method and the system according to the invention may have further applications.

Background

An uncontrolled release of hydrocarbons from a subsea well may be a catastrophic accident. Containing the well during such an accident is essential, and time is a crucial factor. During the tragic Macondo blowout, a number of attempts to contain the release of oil from the well were made. The attempts included using a containment dome, a top kill and junk shot, and a cap for funnelling oil and gas to a surface ship. All failed. Containment was not successful until a capping stack was installed 83 days after the blowout began.

For some wells, a capping stack may need to be deployed from a vessel. This can be done, in situations where the blowout does not comprise gas, by having a vessel position itself directly above the well and deploying and lowering the capping stack to the well from said position. If, however, the blowout does comprise gas, the water above the blowout, above the well, may typically be polluted by gas bubbles. Gas bubbles in water reduces the load-carrying capacity of the water. Thus, a vessel cannot safely move or situate itself directly above the blowout as its buoyancy relative to the sea has been reduced.

The invention presents a way to solve the problem described above, thus making instalment of a capping stack from a vessel a viable option for containment of subsea blowouts comprising gas.

Prior art that some may find relevant is disclosed in documents US 2015308210 A1, WO 2016033278 A1, US 4324505 A, US 2013118754 A1, WO 2010144187 A1, and US

2012275274 A1.

US 2015308210 A1 may be seen as particularly relevant. The document describes a well capping assembly that includes a well cap structure configured to operatively couple to a wellhead structure for capping a fluid flow from a well, and a method of capping an underwater well.

Summary of the invention

According to a first aspect of the invention, there is provided a method for placing an object on a seabed, the method comprising the steps of:
- connecting the object to at least two vessels by use of a work wire;
- co-operating the vessels to move the object into a position that is distant from the vessels, to lower the object to the seabed, and to place the object on the seabed; and
connecting the object and the work wire to one or more buoyancy devices, to achieve a distributed buoyancy of the work wire that forms a double curvature, to improve control and pacing of vertical movement of the object.

According to a second aspect of the invention, there is provided a system for transporting an object to a position in a sea where the water comprises gas bubbles significantly lowering the load-carrying capacity of the water and for lowering the object to an area on a seabed having a wellbore from which the gas bubbles enter the sea, the system comprising:
- at least two vessels; and
- a work wire for connecting the object to the vessels,
wherein the object is connected to the two vessels by use of the work wire, and wherein the system is arranged for holding and lowering the object in a position in the sea distant from the vessels and for placing the object on the seabed, and wherein the work wire is connected to one or more buoyancy devices for achieving a distributed buoyancy of the work wire that forms a double curvature, for improving control and pacing of vertical movement of the object.

Note that “for placing an object on a seabed”/”to place the object on the seabed” is to be understood as to include placing the object directly on the seabed and/or placing the object on a target item or structure that is located in or on the seabed. The object may e.g. be a capping stack to be placed on a wellhead protruding from a seabed or a containment dome to be placed on a seabed to cover a wellhead. The object may otherwise be another object to be used for containment of a blowout or an object that it may be advantageous to

lower to a position on a seabed where the water above said position has its load-carrying capacity reduced due to e.g. gas bubbles in the water.

Note further that the work wire may be any elongated fastening means for fastening two items together suitable for the purpose of connecting an object to at least two vessels and for carrying/supporting said object. It may be e.g. be a rope, a chain or a metal wire. It may be elastic or rigid. A wire may comprise of many parts and/or portions, wherein different portions or parts may consist of different materials and/or be different kinds of wires. The wire connecting the vessels to the object may be seen as one single wire, whether or not it comprises different parts or portions of equal or different types of wires, or it may be seen as a plurality of wires connecting the object to the vessels. E.g. a wire may comprise a section of buoys connected by a chain or a plurality of chains and a section of steel wire, it may comprise nothing but a single piece of steel wire, it may comprise nothing but a chain, it may comprise a multitude of different sections including e.g. one or more chains, one or more steel wires, one or more ropes, one or more buoyancy elements, one or more connector, and more. An advantage of having the wire comprise of different parts may be the it may be to make parts of a wire more rigid whereas another part may advantageously be more flexible, to make one part of a wire more resistant to a type of wear and another part more resistant to another type of wear, etc. An advantage of having a wire comprise nothing but e.g. a length of steel wire may be that the wire is made less complex and/or possible less likely to have one or more weak points.

Note further that the buoyancy elements may be any components with the purpose of providing positive buoyancy. The buoyancy elements may be made from a synthetic material or steel, any combination thereof, or any other material suitable for the purpose. A buoyancy element may comprise many parts and/or portions, wherein different portions or parts may consist of different materials. The buoyancy elements may be different kind of buoys.

“Co-operating the vessels” may include e.g. moving the vessels relative to each other, moving the vessels relative to a position in the sea, and/or using equipment to move the object in the sea and/or to lower the object. The equipment may e.g. be a winch.

By co-operating two or more vessels to move the object into a position and to lower the object, a vessel does not have to position itself directly above or near directly above a blowout well. The vessels can be positioned distant from the blowout. This enables e.g. deploying a capping stack from a vessel to contaminate a blowout when the uncontrolled

release of hydrocarbons comprises hydrocarbon gas.

More than two vessels may be used for the method. The object may be connected to e.g. three or four vessels, or more than four vessels, and moved in place by co-operating the vessels.

"A position that is distant from the vessels" in the context of the claims and the description may be quantitatively defined e.g. as a position at a distance of between 50 meters and 1000 meters from the vessels. The distance may shorter than 50 metres, such as 25 metres, 10 metres or longer than 1000 metres, such as 1200 metres, 2000 metres, 5000 metres, etc. It may e.g. be a distance of between 25 metres and 500 metres, a distance of between 75 metres and 2000 metres, or a distance of between 30 metres and 900 metres.

"A position that is distant from the vessels" may be qualitatively defined, in the context of the claims and the description, as a position a safe distance away from an area of a body of water that is affected by gas bubbles lowering the load-carrying capacity of the water. The gas bubbles may enter the body of water e.g. from a seabed and/or a wellbore. "A position a safe distance away" may be a position wherein the load-carrying capacity of the water is not affected by the gas bubbles or where the effect of the bubbles is so small that one or more vessels being a part of the system according to the invention or for carrying out the method according to the invention can safely move and/or stay without an unacceptable risk of sinking.

The method may comprise the step of adjusting a length of work wire released from a vessel to adjust the position of the object in the sea and/or to lower the object to the seabed. The length of the work wire released may be increased to lower the object in the sea or decreased to raise the object in the sea. The step of adjusting the length may be performed by use of a winch. The system may comprise a means for adjusting the length of released work wire, such as a winch.

Adjusting the length of the work wire may be advantageous to allow for a more accurate and less complicated positioning and lowering of the object than if the length of work wire from one or more vessels was fixed and the only way to move and/or lower the object was to move one or more vessels.

The method may comprise the step of shutting down a well to end an uncontrolled release of gas and/or oil from the well and/or containing an uncontrolled release of hydrocar-

bons/a blowout from a wellbore by placing the object on the seabed to cover the top of the well and/or by placing the object over a top end of the wellbore and/or by connecting the object to a wellbore. The object may be a capping stack and the capping stack may be placed onto a wellhead or otherwise connected to the wellbore to contain an uncontrolled release of hydrocarbons. The object may e.g. be a containment dome, and it may be placed over a top end of the wellbore to contain a blowout. The object may be another object than a containment dome or a capping stack and/or it may be used for other purposes than for containment purposes.

Furthermore, the method may comprise the step of connecting the object to one or more heave-compensating devices other than the buoyancy devices in addition to the buoyancy devices. One or more buoyancy devices are connected to the object via the work wire, e.g. by being arranged around a portion of the work wire. In addition, one or more buoyancy devices may be connected to the object directly. The system may comprise one or more buoyancy devices. Having buoyancy devices connected to the object may be advantageous for improving control and pacing of vertical movement of the object. A plurality of buoyancy devices may be connected to the object. Arranging a plurality of buoyancy devices in connection with the object may be particularly advantageous. Spreading the plurality of buoyancy devices in a symmetrical fashion along the work wire or wires leading from the object to the vessels may be even more advantageous.

One or more buoyancy devices connected to the object may be buoyancy devices having adjustable buoyancy. This may advantageously further increase control and pacing of lowering of the object. The buoyancy device may have adjustable buoyancy e.g. by being arranged for taking in water when the surrounding water pressure increases over a certain threshold or by having a valve that can be opened to take in water. The buoyancy device may be arranged to have its buoyancy increased or to have it decreased. The system may comprise one or more buoyancy devices having adjustable buoyancy.

The method may further comprise the step of connecting a relief wire to the object from at least one of the vessels to carry at least a portion of a gravitational load from the object. The relief wire may be used e.g. to carry a load from the object for deployment of a buoyancy device from a vessel, to avoid having excessive gravitational forces damage the buoyancy devices. The object may be connected by one or more relief wires to more than one vessel. The length of the relief wire released from a vessel may be adjustable, e.g. by use of a winch. The system may comprise one or more relief wires.

An ROV may be used to monitor the position of the object in the water to improve accuracy of the step of co-operating the vessels to lower the object to the seabed. The method may comprise the step to use the ROV to monitor the position of the object. It may further comprise the step to deploy the ROV. Furthermore, the method may comprise the step of using the ROV to monitor the seabed and/or equipment on the seabed. Furthermore, the method may comprise the step of communicating information gathered by the ROV to one or more vessels by use of means for communication of such information. The system may comprise an ROV.

Alternatively, or in addition, a transponder may be used to increase accuracy when lowering/positioning the object. The method may comprise the step of using a transponder placed at or near the object to monitor the position of the object to improve accuracy of the step of co-operating the vessels to lower the object to the seabed. Information gathered from the transponder may be communicated to one or more vessels by use of means for communication of such information. The system may comprise a transponder.

The system may comprise communication means for communicating between the vessels to co-operate in transporting the object and/or in lowering the object to the seabed. Communication means may be highly advantageous to ensure safe and accurate transport and placing of the object. The communication means may comprise means for radio communication, video communication, communication of digital data, and more.

In the following is described an example of a preferred embodiment of the system and an example of the method illustrated in the accompanying drawings, wherein:

Fig. 1 shows an embodiment of the invention, where two vessels are connected to a capping stack and have moved it to a position in a sea over a wellbore;

Fig. 2 shows a capping stack being deployed from a vessel;

Fig. 3 shows two vessels as the work wire is being fed from a first vessel to a second vessel;

Fig. 4 shows the first vessel as a wire for connecting the object to the second vessel and a wire for connecting the object to the first vessel are being connected to each other and to the object via a triplate;

Fig. 5 shows a relief wire being used to carry a load from the object as buoys are being deployed from the vessel; and

Fig. 6 shows the object being suspended from two vessels following deployment of buoyancy devices.

Note that the drawings are schematic and not necessarily drawn to scale.

Figure 1 shows a system 1 for transporting an object 200 to a position in a sea 3 where the water in the sea 3 comprises gas bubbles 23 significantly lowering the load-carrying capacity of the water and for lowering the object 200 to an area on a seabed 31 having a wellbore 2 from which wellbore the gas bubbles 23 enter the sea 3.

The system 1 comprises two vessels 110, 120, two work wires 131, 132, an object-supporting wire 233, a connector 235 for connecting the work wires to each other and to the object-supporting wire 233, and the object 200.

The object 200, in the embodiment shown in the figures, is a capping stack 200 for establishing control of the wellbore 2 which is having a blowout comprising gas, causing the gas bubbles 23 to enter the sea.

The system 1 enables deploying a capping stack 200 or other well-containment equipment from a vessel 110, 120 during a blowout comprising gas, as it allows the vessels 110, 120 involved to keep a safe distance to the blowout site and thus to avoid an area of water having its load-carrying ability reduced.

By using two vessels 110, 120 and two work wires 131, 132 connected to the capping stack 200, the capping stack 200 can safely be moved to the correct position in the sea 3 and lowered to the seabed 31 and/or the wellbore 2. The work wires 131, 132 extending from the vessels 110, 120 to the connector 135 can be 100 metres long but can of course be either longer or shorter. One or more of the vessels 110, 120 can have a winch (not shown) or other means (not shown) for changing the length of released work wire 131, 132 from the vessel or vessels 110, 120. The position of the capping stack 200 in the sea 3 can be changed by moving one or more of the vessels 110, 120 and/or by using the means for changing the length of released work wire or wires 131, 132.

Buoyancy devices 136 are fastened to the work wires 131, 132, to increase the buoyancy near the capping stack 200. The increased buoyancy provided by the buoyancy can e.g. improve accuracy when lowering the capping stack 200 to the seabed 31.

The system 1 may also be used to raise equipment from the seabed 31 in a sea where gas bubbles decreases the load-carrying capacity of the water.

Figure 2 shows how a capping stack 200 to be used as part of the system 1 can be deployed. This can typically be done by use of a crane (not shown) from a dock or a barge (not shown) or a crane or an A-frame (not shown) aboard the vessel 110. The capping stack 200 is hoisted to a vessel 110 and connected to the vessel 110 by use of a work wire 131 and a tugging wire 170 and suspended by use of said wires 131, 170 from the stern of the vessel 110. The end portion of the tugging wire 170 has a tugger 171 for tugging the capping stack 200 to avoid or decrease movement of the capping stack 200 while its suspended from the stern of the vessel 110.

As a next step of the method, the vessel 110 and a second vessel 120 can typically travel to an area near a blowout-site. When reaching the area, the capping stack 200 may be connected to both vessels 110, 120 and subsequently deployed into the sea 3.

In Figure 3 it is shown how a work wire 131 of one vessel 110 can be connected to a work wire 132 of another vessel 120. The two vessels 110, 120 align stern-to-stern, and the work wire 131 of the second vessel 120 is passed to the first vessel 110. In the embodiment shown in Figure 3, the work wire 132 of the second vessel 120 has a buoy sling 134 comprising a plurality of buoyancy devices 136 in the form of buoys 136. When the work wire 132 of the second vessel has been passed to the first vessel 110 it can be connected to the work wire 131 of the first vessel 110.

Furthermore, Figure 3 shows the capping stack 200 suspended from the stern of the first vessel 110.

Figure 4 shows the first vessel 110 having the work wire 132 of the second vessel 120 (not shown) on its deck and connected by use of a connector 235 in the form of a triplate 235 to the work wire 131 of the first vessel 110. The connector 235 can of course be another type of connector 235 suitable for the purpose. Furthermore, the capping stack 200 is shown suspended from the stern of the first vessel 110 and connected to an object-supporting wire 233. The object-supporting wire 233 is about to be connected by use of the connector 235 to the work wires 131, 132.

Figure 5 shows the capping stack 200 being suspended from the first vessel 110 by use of a relief wire 139 and from the second vessel (not shown) by use of the work wire 132 of the second vessel 120 as buoyancy devices 136 in the form of buoys are being deployed from the first vessel 110. This is done to reduce the gravitational load from the capping stack 200 affecting the buoys 136 as they are moved off the stern of the first vessel 110, to avoid damaging the buoys 136.

In Figure 6, the capping stack 200 is shown suspended from the work wires 131, 132 from the two vessels 110, 120 via the object-supporting wire 233, following deployment of all buoyancy devices 136. The relief wire 139 no longer carries load from the capping stack 200.

When the capping stack 200 and the buoyancy devices 136 have been deployed, the vessels 110, 120 travel into a position in the sea where the water safely carries their weight while simultaneously moving the capping stack 200 into a position where gas bubbles 23 reduce the load-carrying capacity of the water, as seen in Figure 1. While travelling into position, the necessary length of work wire 131, 132 is released from the vessels 110, 120.

When the two vessels 110, 120 and the capping stack 200 are in position, the object can be lowered to the seabed 31 and mounted onto a wellhead or otherwise connected to the well.

During lowering of the capping stack 200 to the seabed 31, an ROV and/or a transponder can be used, or any other means for providing information on the location of the capping stack 200 in the sea 3 and/or the position of the capping stack 200 relative to the seabed 31 and/or well. The capping stack 200 can be lowered to the seabed through movement of one or more of the vessels 110, 120 and/or by use of a means of paying out or pulling in work wire 131, 132.

C l a i m s

1. A method for placing an object (200) on a seabed (31), the method comprising the steps of:
- connecting the object (200) to at least two vessels (110, 120) by use of a work wire (131, 132); and
- co-operating the vessels (110, 120) to move the object (200) into a position in a sea (3) distant from the vessels (110, 120), to lower the object (200) to the seabed (31) and to place the object (200) on the seabed (31) , the method being c h a r a c t e r i s e d i n that it further comprises the step of:
- connecting the object (200) and the work wire (131, 132) to one or more buoyancy devices (136), to achieve a distributed buoyancy of the work wire (131, 132) that forms a double curvature, to improve control and pacing of vertical movement of the object (200).

2. The method according to claim 1, wherein the method comprises the step of:
- adjusting a length of the work wire (131, 132) released from the vessels (110, 120) to adjust the position of the object (200) in the sea (3) and/or to lower the object (200) to the seabed (31).

3. The method according to claim 1 or claim 2, wherein the object (200) is a capping stack (200) and wherein the method further comprises the step of:
- containing an uncontrolled release of hydrocarbons from a wellbore (2) by connecting the capping stack (200) to the wellbore (2).

4. The method according to any one of the preceding claims, wherein at least one of the at least one or more buoyancy devices (136) is a buoyancy device (136) having adjustable buoyancy, wherein the method further comprises the step of:
- adjusting the buoyancy of the buoyancy device (136) having adjustable buoyancy.

5. The method according to any one of the preceding claims, wherein the method comprises the step of:
- shutting down the wellbore (2) to end an uncontrolled release of gas and/or oil from the well by placing the object (200) on the seabed (31) to cover the top of the wellbore (2).

6. The method according to any one of the preceding claims, wherein the method comprises the step of:
- connecting a relief wire (139) to the object (200) from at least one of the vessels (110, 120) to carry at least a portion of a gravitational load from the object (200).

7. The method according to claim 6, wherein the relief wire (139) is used to carry a gravitational load from the object (200) while performing the step of:
- deploying the one or more buoyancy devices (136) from the vessels (110, 120).

8. The method according to any one of the preceding claims, wherein the method further comprises the steps of:
- deploying an ROV; and
- using the ROV to monitor the position of the object (200) to improve accuracy of the step of co-operating the vessels (110, 120) to lower the object (200) to the seabed (31).

9. The method according to any one of the preceding claims, wherein the method further comprises the step of:
- using a transponder placed at or near the object (200) to monitor the position of the object (200) to improve accuracy of the step of co-operating the vessels (110, 120) to lower the object (200) to the seabed (31).

10. A system (1) for transporting an object (200) to a position in a sea (3) where the water comprises gas bubbles (23) significantly lowering the load-carrying capacity of the water and for lowering the object (200) to an area on a seabed (31) having a wellbore (2) from which the gas bubbles (23) enter the sea (3), the system (1) comprising:
- at least two vessels (110, 120); and
- a work wire (131, 132) for connecting the object (200) to the vessels (110, 120), wherein the object (200) is connected to the two vessels (110, 120) by use of the work wire (131, 132),and wherein the system (1) is arranged for holding and lowering the object (200) in a position in the sea (3) distant from the vessels (110, 120) and for placing the object (200) on the seabed (31),
the system (1) being c h a r a c t e r i s e d i n that the work wire (131, 132) is connected to one or more buoyancy devices (136) for achieving a distributed buoyancy of the work wire (131, 132) that forms a double curvature, for improving control and pacing of vertical movement of the object (200).

11. The system (1) according to claim 10, wherein the vessels (110, 120) comprises communication means for communicating between the vessels (110,120) to co-operate in transporting the object (200) and/or in lowering the object (200) to the seabed (31).

12. The system (1) according to any one of claim 10 or 11, wherein the system (1) further comprises a transponder located on or close to the object (200) and/or an ROV for providing data on the position of the object (200) in the sea (3).

13. The system (1) according to any one of claims 10 or 12, where at least one of the one or more buoyancy devices (136) has adjustable buoyancy.

14. The system (1) according to any one of claims 10 to 13, wherein the system (1) comprises a relief wire (139) for carrying at least a portion of a gravitational load from the object (200), wherein said relief wire (139) is connected to the object (200) and to at least one of the vessels (110, 120).

P a t e n t k r a v

1. Fremgangsmåte for plassering av en gjenstand (200) på en havbunn (31), idet fremgangsmåten omfatter trinnene:

- å koble gjenstanden (200) til minst to fartøy (110, 120) ved anvendelse av en arbeidsvaier (131, 132); og

- å samstyre fartøyene (110, 120) for å flytte gjenstanden (200) til en posisjon i et hav (3) på avstand fra fartøyene (110, 120), for å senke gjenstanden (200) til havbunnen (31) og for å plassere gjenstanden (200) på havbunnen (31), idet fremgangsmåten er k a r a k t e r i s e r t v e d at den videre omfatter trinnet:

- å koble gjenstanden (200) og arbeidsvaieren (131, 132) til én eller flere oppdriftsanordninger (136), for å oppnå en fordelt oppdrift i arbeidsvaieren (131, 132) som tildanner en dobbel kurvatur, for å forbedre kontroll og hastighetsregulering av vertikal bevegelse av gjenstanden (200).

2. Fremgangsmåte ifølge krav 1, hvor fremgangsmåten omfatter trinnet:

- å justere en lengde av arbeidsvaieren (131, 132) som slippes ut fra fartøyene (110, 120) for å justere posisjonen til gjenstanden (200) i havet (3) og/eller for å senke gjenstanden (200) til havbunnen (31).

3. Fremgangsmåte ifølge krav 1 eller krav 2, hvor gjenstanden (200) er en capping stack (200) og hvor fremgangsmåten videre omfatter trinnet:

- å holde igjen et ukontrollert utslipp av hydrokarboner fra et borehull (2) ved å koble capping stack-en (200) til borehullet (2).

4. Fremgangsmåte ifølge et hvilket som helst av de foregående kravene, hvor minst én av den minst ene eller flere oppdriftsanordningene (136) er en oppdriftsanordning (136) som har justerbar oppdrift, hvor fremgangsmåten videre omfatter trinnet:

- å justere oppdriften til oppdriftsanordningen (136) som har justerbar oppdrift.

5. Fremgangsmåte ifølge et hvilket som helst av de foregående kravene, hvor fremgangsmåten omfatter trinnet:

- å stenge ned borehullet (2) for å avslutte et ukontrollert utslipp av gass og/eller olje fra brønnen ved å plassere gjenstanden (200) på havbunnen (31) for å dekke toppen av borehullet (2).

6. Fremgangsmåte ifølge et hvilket som helst av de foregående kravene, hvor fremgangsmåten omfatter trinnet:

- å koble en avlastningsvaier (139) til gjenstanden (200) fra minst ett av fartøyene (110, 120) for å bære i det minste en del av en gravitasjonslast fra gjenstanden (200).

7. Fremgangsmåte ifølge krav 6, hvor avlastningsvaieren (139) anvendes til å bære en gravitasjonslast fra gjenstanden (200) under utførelse av trinnet:

- å sende ut den ene eller flere oppdriftsanordningene (136) fra fartøyene (110, 120).

8. Fremgangsmåte ifølge et hvilket som helst av de foregående kravene, hvor fremgangsmåten videre omfatter trinnene:

- å sende ut et fjernstyrt undervannsfartøy; og

- å anvende det fjernstyrte undervannsfartøyet til å overvåke posisjonen til gjenstanden (200) for å forbedre nøyaktigheten av trinnet å samstyre fartøyene (110, 120) for å senke gjenstanden (200) til havbunnen (31).

9. Fremgangsmåte ifølge et hvilket som helst av de foregående kravene, hvor fremgangsmåten videre omfatter trinnet:

- å anvende en transponder som er plassert på eller i nærheten av gjenstanden (200), til å overvåke posisjonen til gjenstanden (200) for å forbedre nøyaktigheten av trinnet å samstyre fartøyene (110, 120) for å senke gjenstanden (200) til havbunnen (31).

10. System (1) for transport av en gjenstand (200) til en posisjon i et hav (3), hvor vannet omfatter gassbobler (23) som betydelig reduserer den lastbærende kapasiteten til vannet, og for senking av gjenstanden (200) til et område på en havbunn (31) som har et borehull (2) hvorfra gassboblene (23) kommer ut i havet (3), idet systemet (1) omfatter:

- minst to fartøyer (110, 120); og

- en arbeidsvaier (131, 132) for å koble gjenstanden (200) til fartøyene (110, 120), hvor gjenstanden (200) er koblet til de to fartøyene (110, 120) ved anvendelse av arbeidsvaieren (131, 132), og hvor systemet (1) er anordnet for å holde og senke gjenstanden (200) i en posisjon i havet (3) på avstand fra fartøyene (110, 120) og for å plassere gjenstanden (200) på havbunnen (31), idet systemet (1) er k a r a k t e r i s e r t v e d at arbeidsvaieren (131, 132) er koblet til én eller flere oppdriftsanordninger (136) for å oppnå en fordelt oppdrift i arbeidsvaieren (131, 132) som tildanner en dobbel kurvatur, for å forbedre kontroll og hastighetsregulering av vertikal bevegelse av gjenstanden (200).

11. System (1) ifølge krav 10, hvor fartøyene (110, 120) omfatter kommunikasjonsmidler for kommunikasjon mellom fartøyene (110, 120) for å samstyre transport av gjenstanden (200) og/eller senking av gjenstanden (200) til havbunnen (31).

12. System (1) ifølge et hvilket som helst av kravene 10 eller 11, hvor systemet (1) videre omfatter en transponder beliggende på eller i nærheten av gjenstanden (200) og/eller et fjernstyrt undervannsfartøy for å tilveiebringe data om posisjonen til gjenstanden (200) i havet (3).

13. System (1) ifølge et hvilket som helst av kravene 10 eller 12, hvor minst én av den ene eller flere oppdriftsanordningene (136) har justerbar oppdrift.

14. System (1) ifølge et hvilket som helst av kravene 10 til 13, hvor systemet (1) omfatter en avlastningsvaier (139) for å bære i det minste en del av en gravitasjonslast fra gjenstanden (200), hvor nevnte avlastningsvaier (139) er koblet til gjenstanden (200) og til minst ett av fartøyene (110, 120).

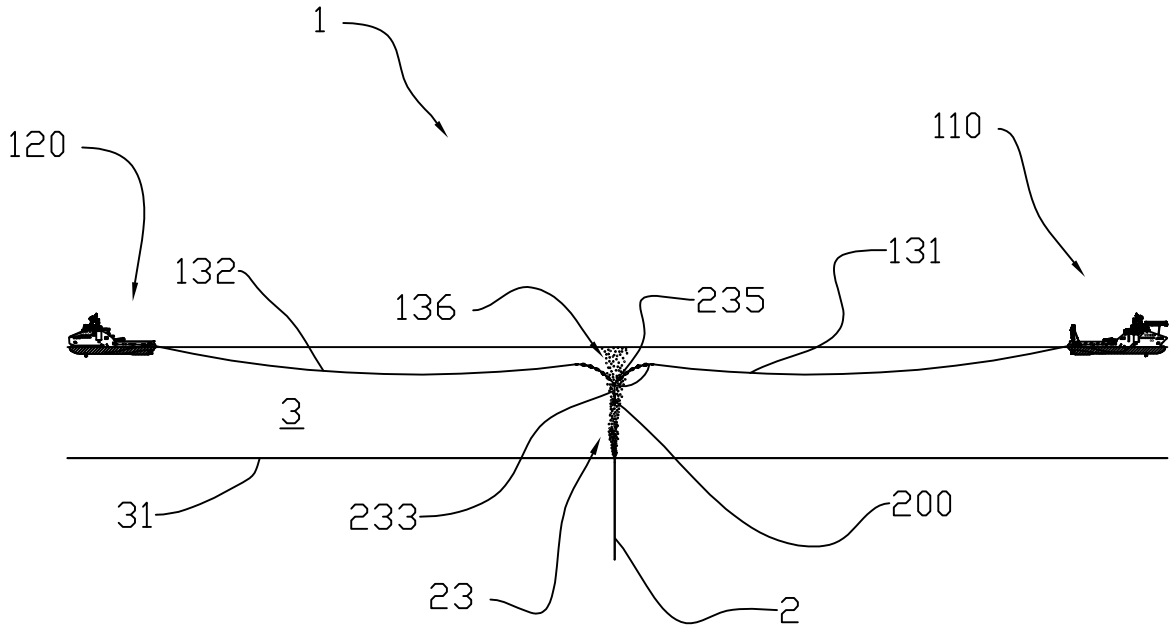


Fig. 1

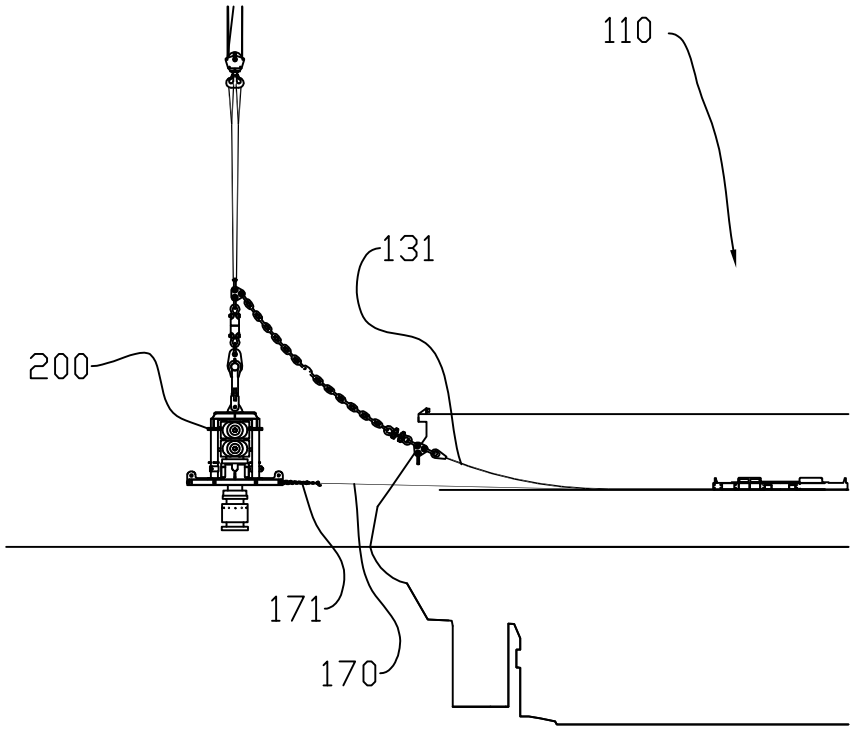


Fig. 2

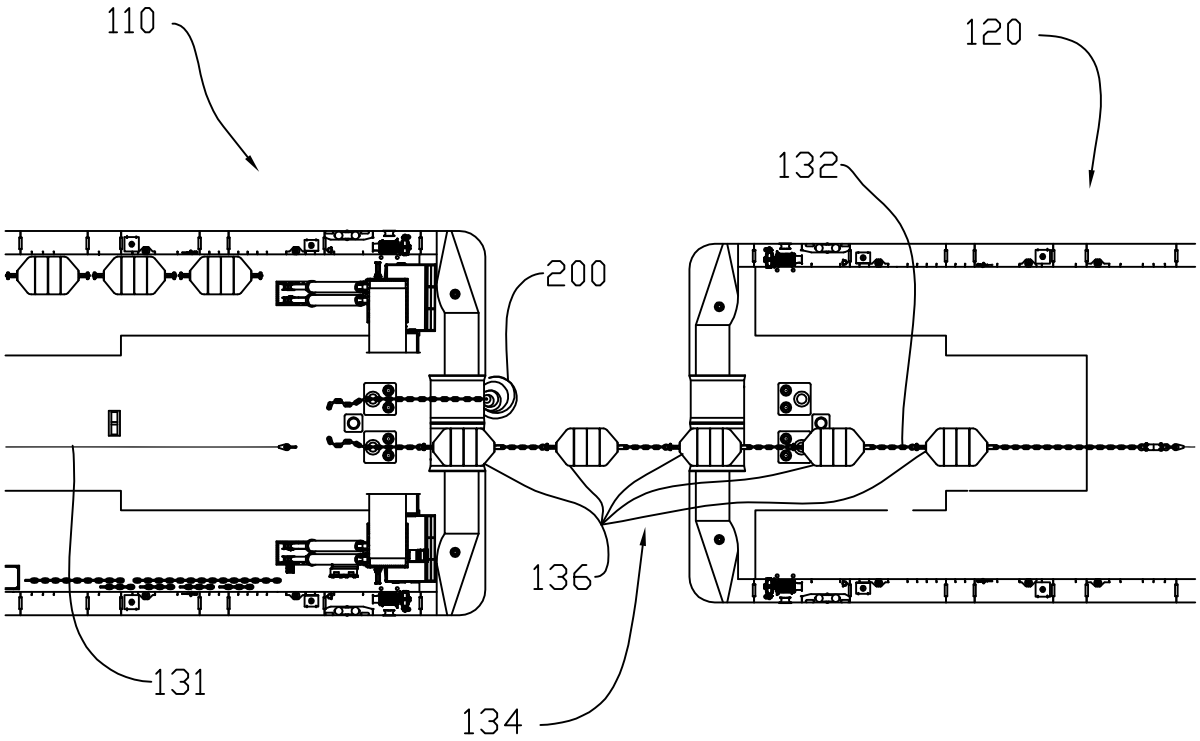


Fig. 3

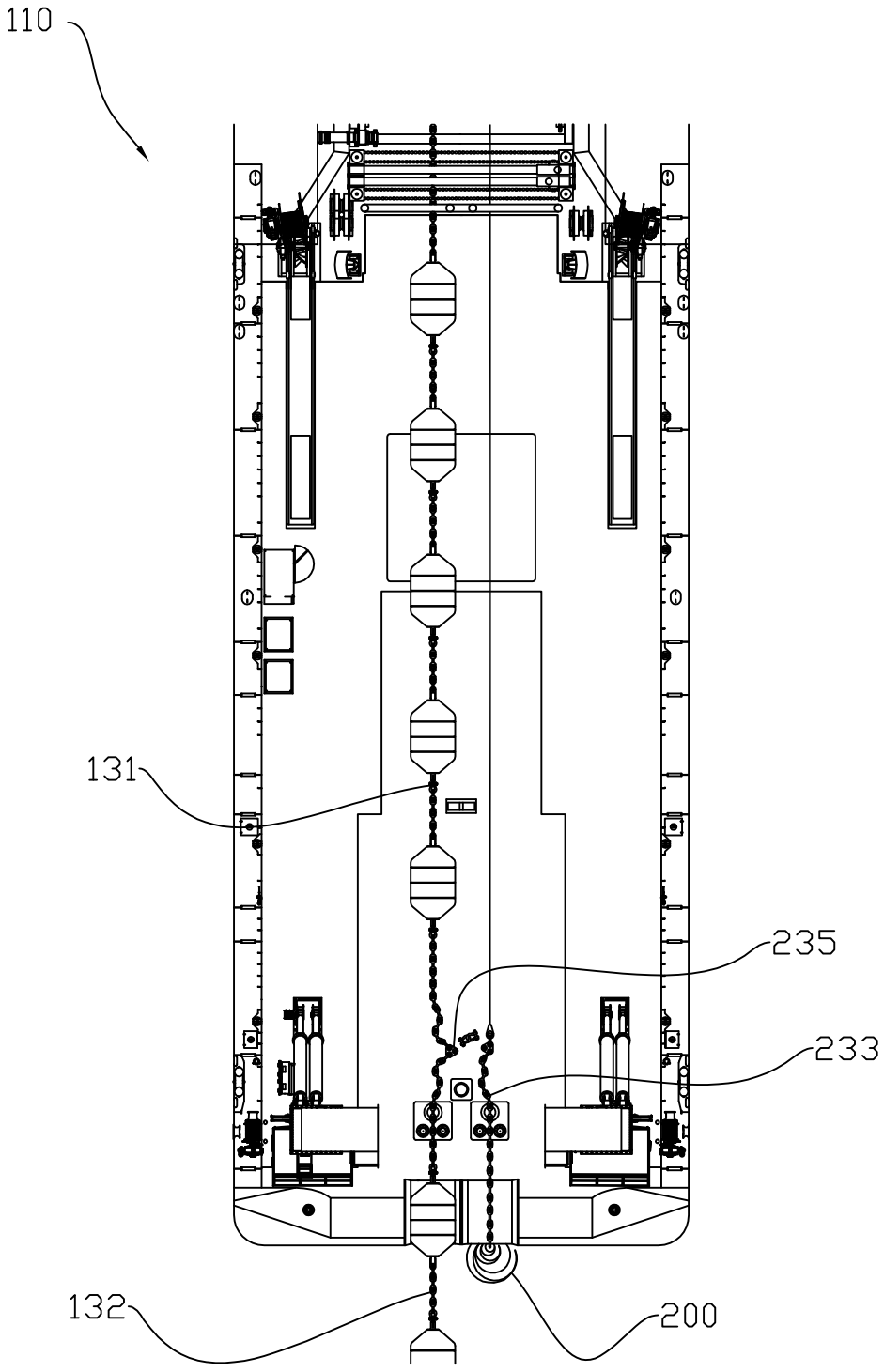


Fig. 4

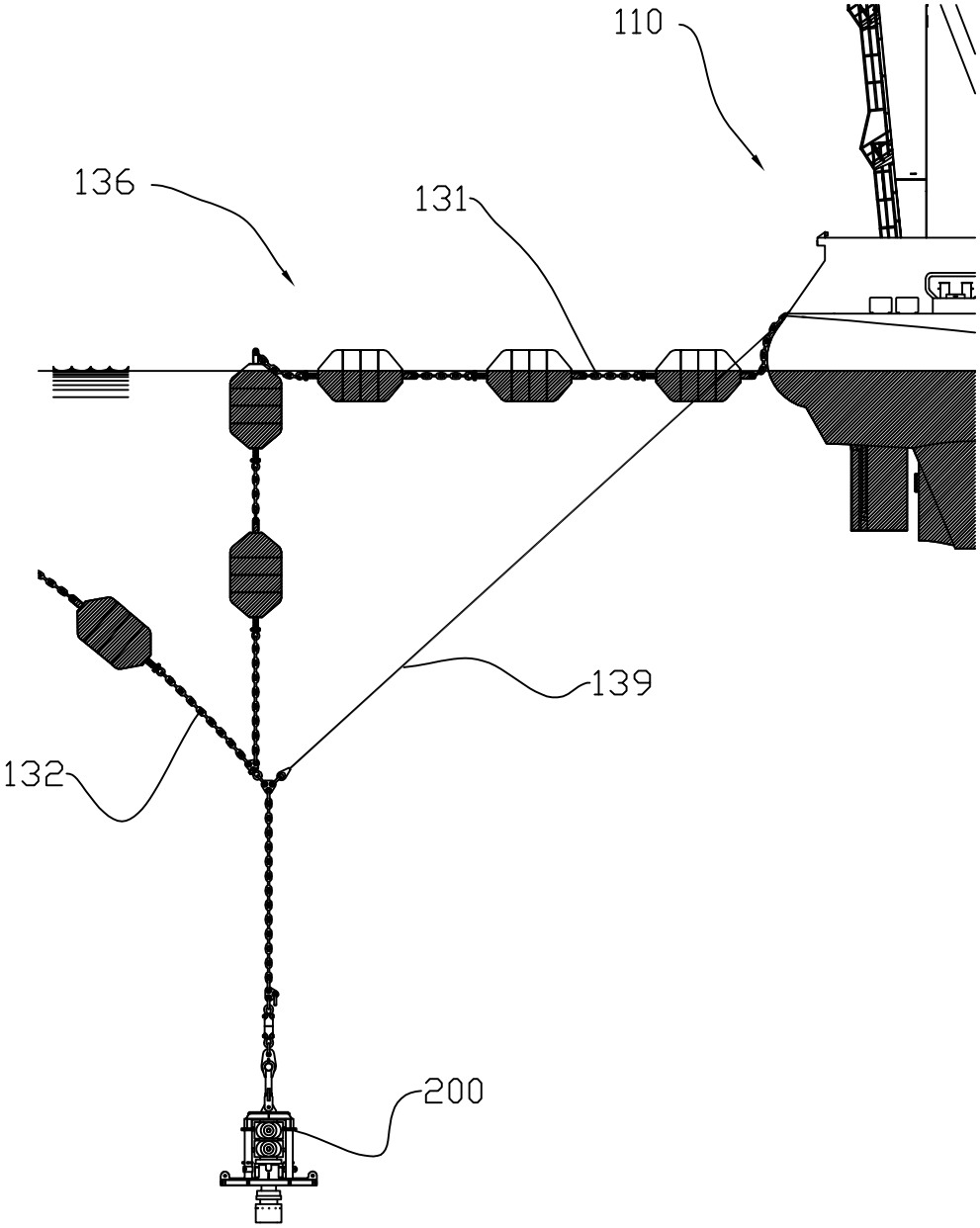


Fig. 5

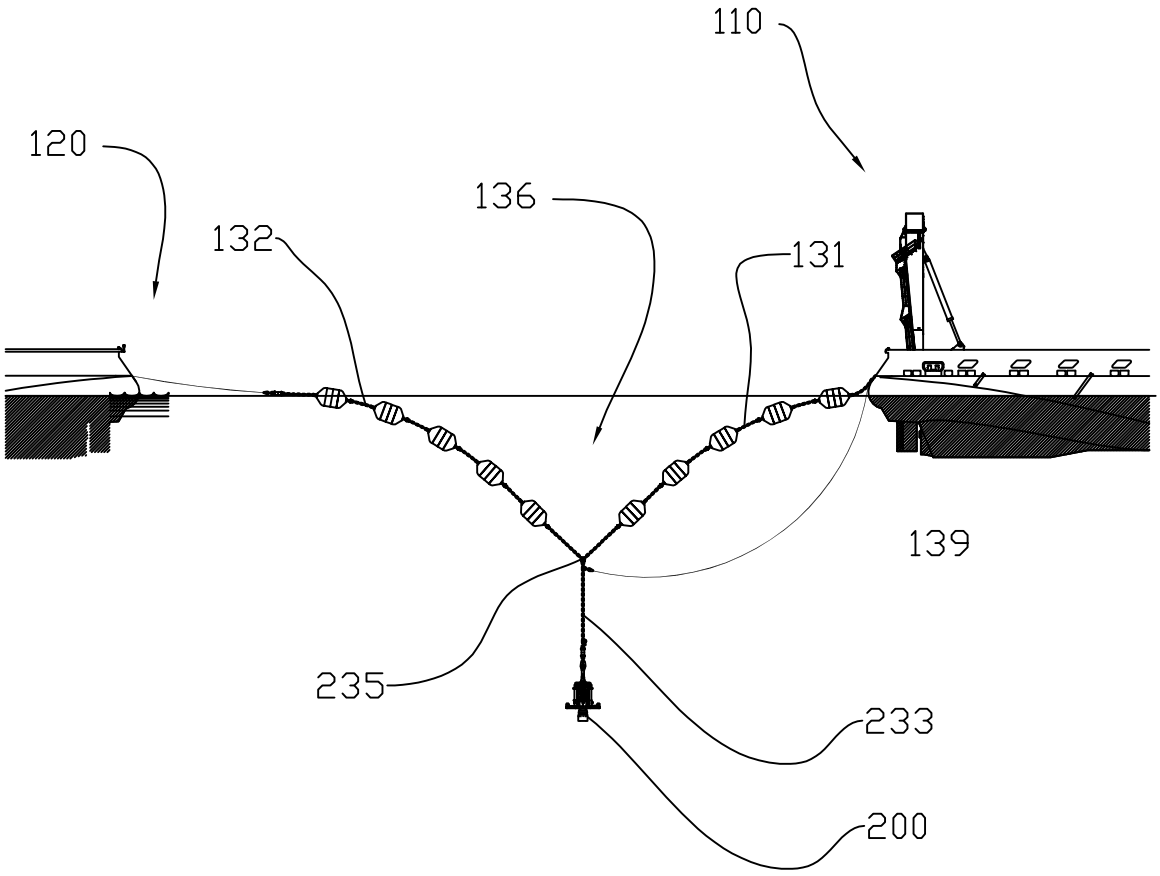


Fig. 6