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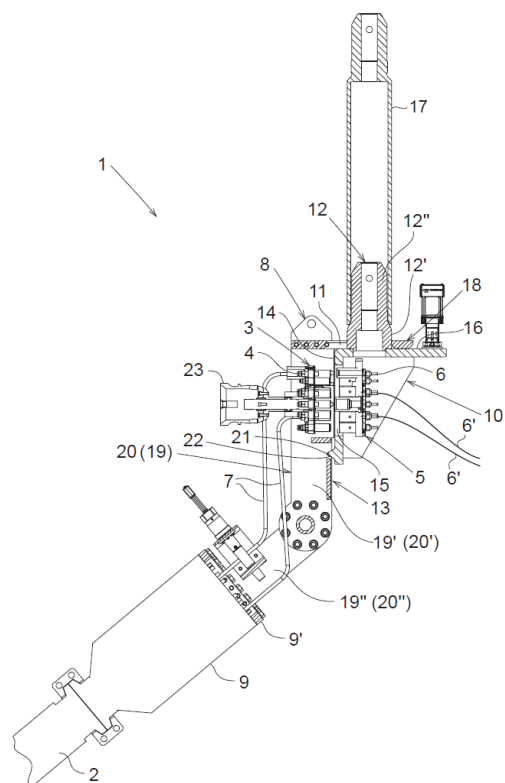
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(54)	Title	A connection system for a multi-bore flying lead or umbilical
(56)	References Cited:	US 2015/0176340 A1, US 2014/186120 A1, US 2010/0059229 A1
(57)	Abstract	

A connection system (1) for a multi-bore flying lead or umbilical (2) the connection system comprising a first connector part (3) having a number of couplers (4), a second connector part (5) having a corresponding number of couplers (6), wherein the first connector part (3) is suspended in ends of associated conduits (7), the conduits extending from one end of the multi-bore flying lead or umbilical (2) into the couplers (4) arranged in the first connector part (3), and wherein the second connector part (5) is mounted stationary in a holding fixture (10). Interacting guide means (11; 12) are arranged on the holding fixture (10) and on a bracket (8) that is anchored in said one end (9) of the flying lead or umbilical (2) respectively, to bring the first and second connector parts into mating position through a guided, relative motion.



A connection system for a multi-bore flying lead or umbilical

TECHNICAL FIELD OF THE INVENTION

The present invention relates to a connection system for a multi-bore flying lead or umbilical, the connection system comprising a first connector part having a number of couplers associated with internal conduits of the multi-bore flying lead or umbilical, a second connector part having a corresponding number of couplers associated with internal conduits of a subsea structure, wherein in a mating position between the first and second connector parts, the first connector part can be pulled towards the second connector part for connection of said couplers.

BACKGROUND AND PRIOR ART

In the subsea industry, a connector for the subject purpose is often referred to as a “Cobra Head”. A cobra head is a device which provides termination and tying-in of a flying lead or umbilical between subsea equipment such as between the subsea umbilical termination assembly (SUTA) and a subsea distribution unit (SDU), a Christmas tree (XT), a manifold or flow-base structure, etc. A cobra head is outfitted with a number of wet-matable couplers corresponding to the number of conduits in the flying lead or umbilical. The couplers are assembled in a multiple quick connection (MQC) plate, also referred to as an outboard or flying MQC plate, which can be pulled in and coupled to a corresponding MQC plate which is mounted stationary inboard of the subsea equipment. Connection is typically accomplished by means of an ROV (remotely operated vehicle) operated flying lead orientation tool (FLOT)/torque tool that positions and engages the coupler plates to pull them together in a rotary motion of the tool. The term cobra head originates from the appearance of a flying lead lying on the seafloor when the flying MQC plate is lifted by the ROV assisted by a buoyancy element for coupling with the fixed MQC plate, thus reminding of the appearance of a striking cobra.

A prior example of a cobra head can be seen in US 2010/0059229 A1. This document discloses a connector device wherein MQC plates of different brands, sizes or designs can be attached to the frame structure of the cobra head using exchangeable interface elements. US 2010/0059229 A1 also explains the

predominantly used method for positioning the MQC plates into mating position upon connecting, a method which includes flying the cobra head into position using an ROV which is assisted by a buoyancy aid that is temporary or permanently attached to the flying lead end.

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Regardless of being permanently attached or detachable, the float that provides buoyancy to the flying lead end for mating the MQC plates occupies a volume that reduces the available space for ROV manoeuvres and increases drifting caused by underwater currents.

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Another drawback in prior art cobra head connection systems is that all forces from the cobra head and flying lead/umbilical goes directly or partly through the MQC plates.

15 SUMMARY OF THE INVENTION

It is an object of the present invention to provide a connection system for a multi-bore flying lead or umbilical which avoids the drawbacks of prior art cobra head connection systems.

20 It is a special object of the present invention to provide a connection system which avoids the need for bulky floats to fly the connector parts into a mating position.

It is another special object of the present invention to provide a connection system by which the connector parts are relieved from forces resulting from the structural
25 weight of the flying lead or umbilical in connected mode.

One or several of these objects will be met in a connection system for a multi-bore flying lead or umbilical according to claim 1.

30 Briefly, the connection system comprises a first connector part having a number of couplers associated with internal conduits of the multi-bore flying lead/umbilical. A second connector part has a corresponding number of couplers associated with internal conduits of a subsea structure. The first connector part is suspended

floating in the free ends of associated conduits, said conduits extending non-constrained from the end of the multi-bore flying lead/umbilical into a bracket that is anchored in said end of the flying lead/umbilical. The second connector part is mounted stationary in a holding fixture.

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In a mating position the first connector part can be pulled towards the second connector part for connection due to an inherent flexibility in the non-constrained conduits within the bracket.

- 10 In other words, the invention relates to a connection system for a multi-bore flying lead or umbilical, the connection system comprising a first connector part having a number of couplers, a second connector part having a corresponding number of couplers, wherein the first connector part is suspended in ends of associated conduits, the conduits are extending from one end of the multi-bore flying lead or
- 15 umbilical into the couplers arranged in the first connector part, and wherein the second connector part is mounted stationary in a holding fixture, and further wherein in a mating position the first connector part can be pulled towards the second connector part for connection, wherein interacting guide means are arranged on the holding fixture and on a bracket that is anchored in said one end of
- 20 the flying lead or umbilical, the interacting guide means comprising an eye on the bracket and a guide post rising from the holding fixture, wherein the eye is arranged insertable from above on the guide post to bring the first and second connector parts into mating position through a guided descending motion of the first connector part in relation to the second connector part, and that the first connector
- 25 part is suspended floating in free ends of associated conduits, said conduits extending non-constrained from the end of the multi-bore flying lead or umbilical into the bracket.

- The interacting guide means have the combined benefit of simplifying the
- 30 connection process and transferring load from the connectors to a separate holding structure.

More specifically, in some embodiments the interacting guide means are arrangeable on the bracket and on the holding fixture respectively, to bring the first and second connector parts into mating position through a guided, relative motion, especially through a guided vertical relative motion.

5

In other words, the connector parts will be mated through a descending or lowering motion without any need for buoyancy equipment, and without requiring heavy ROV work. Hanging from a crane on a surface vessel, the first and flying connector part only requires ROV observation or assistance to bring the guiding means into alignment, where after gravity is allowed to pull the lowering connector part into mating position with the stationary connector part.

10

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It will be realized that the interacting guide means can be differently structured as long as they provide in cooperation a controlled relative motion which is positively stopped as the lowering connector part reaches the mating position. For example, an interacting guide means for controlling the lowering motion can be arranged in the form of a linear guide track on one of the connector parts engaged by a guide pin arranged on the other connector part. Thus, in accordance with the present invention, the “cobra head” is urged into position for connection by the influence of gravity and the geometric design of the two meeting parts.

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In one embodiment, at least one eye is formed on the bracket and arranged for insertion from above on at least one upright guide post that rises from the holding fixture. It could also be described as an eye on the bracket being arranged insertable from above on a guide post rising from the holding fixture.

25

This embodiment is a non-complex solution. The embodiment also facilitates initial alignment of the guide means if the guide post is formed with an introductory or upper length of reduced diameter, thus requiring less precision in the ROV operation for inserting the guide post through the eye.

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It should be noted that the bracket and the holding fixture are remained in position by the structure weight of the multi-bore flying lead or umbilical as the eye is fully

inserted on the guide post. In some embodiments, the guide post of the above system rises from a top surface adjoining a front face on the holding fixture.

Thus, in one embodiment, the guide post comprises a lower end portion with a
5 larger radius mating with the radius of the eye on the bracket, adjoining an upper end portion of smaller radius. More specifically, the guide post comprises a lower end portion with a first radius, and an upper portion of a second radius, the first radius being larger than the second radius. The upper end portion of smaller radius may be adapted for temporary insertion of a guide post extension over the guide
10 post, in this way extending the guided length of the lowering motion. Thereby, a guide post extension is insertable over the guide post. This auxiliary guide post prolongs the connecting interface between the cobra head of the flying lead or umbilical and the subsea structure to which the flying lead or umbilical will be connected, thereby facilitating navigating of the first connector part onto the second
15 connector part, the second connector part being part of the subsea structure.

In mating position, the second connector part is accessible for connection via a window that is formed in a front face of the holding fixture. A top surface adjoining the front face supports the lower end of the guide post.

20

With a view to the bracket of the system, in some embodiments, the bracket comprises a distal leg portion connected pivotally to a proximal leg portion, the latter fixedly connected to an end fitting of the multi-bore flying lead or umbilical. The bracket comprises a front face which is oriented oppositely to the front face of
25 the holding fixture as the eye is fully inserted on the guide post.

In some embodiments of the system, the eye is formed in a plate-like bracket member protruding from the distal end of the bracket to be received in overlapping relation with the top surface of the holding fixture in mating position. The plate-like
30 bracket member will take load from the couplers area of the connection system and transfer it to a less critical part of the subsea structure, i.e. the top surface of the structure.

A lug, protruding in the front face of the holding fixture, may be arranged to engage a seat that is formed in the opposite face of the bracket. In mutual engagement, the lug and seat provide confirmation that the connector parts have reached the mating position. In other words, wherein the lug in the front face of the holding fixture
5 protrudes for engagement with a seat formed in an opposite front face of the bracket in the mating position.

The eye can be formed in a bracket member that connects the upper ends of two adjoining legs of the bracket. Each leg of the bracket comprising a distal leg portion
10 connectable to a proximal leg portion at an adjustable intermediate angle, the proximal leg portion being fixedly connected to an end fitting of the multi-bore flying lead or umbilical.

The connecting bracket member that forms the eye can a plate which reaches
15 forward from the distal end of the bracket to be received in overlapping relation with the top surface of the holding fixture in the mating position.

From the above it will be realized that all structural load and external forces are taken up by the landing interface as the bracket is landed on the holding fixture,
20 thus relieving the connector parts, or the MQC plates, from external forces and structural loads.

SHORT DESCRIPTION OF THE DRAWINGS

In the following, embodiments of the invention will be more closely described with
25 reference made to the drawings. In the drawings:

Fig. 1 is a partly sectioned elevational view of the connection system in mating position and in non-connected mode, and

Figs. 2A-2D illustrate the sequential steps in a process for mating a moving
30 connector part with a stationary connector part of the present connection system.

DETAILED DESCRIPTION OF PREFERRED EMBODIMENTS

For the purpose of disclosure, a multi bore flying lead or umbilical shall be understood as a flexible or semi-flexible multi-conduit structure designed to convey fluids, electricity or optical signals through internal tubing or cables between items of subsea equipment. The couplers mentioned in the disclosure and claims can thus

either be hydraulic/pneumatic couplers, optic couplers or electric couplers. Accordingly, the first and second connector parts can be equipped with either kind of couplers or a mix of couplers for fluids, electricity or light respectively. However, if not otherwise stated, any mentioning herein of a multi-bore flying lead alone shall be understood to include also a corresponding multi-conduit umbilical as the alternative conveying structure.

In Fig. 1, reference number 1 denotes generally a connection system by which a multi-bore flying lead 2 can be connected to an item of subsea equipment. The subsea equipment in question can be any arbitrary subsea device and its representation is not required in the drawing for the purpose of illustrating the connection system 1.

The connection system 1 comprises a first connector part 3 carrying a number of couplers 4. The couplers 4 are arranged for coupling with corresponding couplers 6 carried on a second connector part 5.

The first connector part 3 is suspended in the ends of conduits (steel tube or flexible hoses) 7 that extend from the end of the flying lead 2 into a bracket 8, the bracket 8 being anchored in a bulk-head plate or an end fitting 9 of the flying lead 2. More precisely, the bracket 8 is bolted to the rim of an end flange 9' attached in the extreme end of the end fitting 9.

The conduits 7 extend unconstrained within the bracket 8 from the flying lead end 9 to the associated couplers 4 in the first connector part 3. Thus, the first connector part 3 can be regarded as being suspended floating in the free/unconstrained ends of the conduits 7, due to an inherent flexibility in the conduits 7. In this connection, the capacity of "floating" refers to the ability of pulling the first connection part 3

towards the second connector part 4 by the operation of an ROV tool, which can be brought to engage the ROV handle 23 installed on the first connector part 3.

The bracket 8 is a structure comprising a couple of parallel legs, 19 and 20, of which only the distant leg 19 is visible in the sectioned drawing of Fig. 1 (see also Fig. 2B). Each leg comprises a distal leg portion 19' or 20' which is pivotally connected to a proximal leg portion 19", 20" under an adjustable intermediate angle. The proximal leg portion 19", 20" is the part of the bracket that is anchored in the end of the umbilical/flying lead.

A plate-like bracket member 18 connects the distal ends of the legs 19 and 20. The connecting bracket member 18 extends forward from the legs, defining an eye 11 that forms one part of an interacting guide means that controls the first connector part 3 in a lowering motion that brings the connector parts 3 and 5 into mating position.

The second connector part 5 is stationary mounted in a holding fixture 10 which is secured in the structure of the connectable subsea equipment. Internal conduits 6' of the subsea structure connect to associated couplers 6 in the second connector part 5. The holding fixture 10 has a top surface 16 supporting an upright guide post 12 that forms the other part of the interacting guide means. In the mating position shown in Fig. 1, the eye 11 is fully inserted on the guide post 12, the bracket member 18 landed on the top surface 16 for a load bearing contact at the landing interface 16-18.

The guide post 12 has a lower end portion 12' with a larger radius closely corresponding with the radius of the eye 11. An upper portion 12" of the guide post has a smaller radius adapted for insertion of a guide post-extension 17 over the guide post 12. The guide post extension may be used temporarily during lowering of the bracket and the first connector part 3 if weather conditions or other conditions so require.

In the holding fixture 10, the top surface 16 adjoins a front face 14 facing the bracket 8 with the first connector part 3. A window 15 in the front face 14 provides access to the second connector part 5 for connection of couplers 4 and 6 in the mating position.

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In the mating position, the structural weight of the flying lead 2 acts to pull the bracket 8 and the first connector part 3 down, thus maintaining the mating position in which connection can be accomplished. A lug 21 that protrudes in the vertical face 14 of the holding fixture 10 defines the mating position by engagement with a
10 seat 22 formed in the opposite face 13 of the bracket 8, as the faces 13 and 14 are facing each other in the mating position.

The process of mating the connector parts will now be briefly explained with reference to Figs. 2A-2D. Fig. 2A shows installation of the guide post extension 17
15 on the guide post 12. In Fig. 2B, the moving connector part is lowered through the water volume hanging from a strap 24 that is connected to eyelets 25 formed in the upper end of the bracket 8. The strap is typically fed out from a vessel on the surface, the lowering motion thus driven by gravity. In Fig. 2C, the bracket 8 has landed on the holding fixture 10, guided in position as the eye 11 slides down along
20 guide post extension 17 and the guide post 12 respectively. Finally, in Fig. 2D, the guide post extension 17 may be detached.

In the mating process, aligning the eye and the guide post/guide post extension can be accomplished using an ROV as the bracket is closing in on the holding fixture.

25 Aligning of the two assemblies may alternatively be accomplished on the surface vessel by insertion of the eye 11 on a lowering line 26 used for installation and retrieval of the guide post extension 17, if appropriate.

CLAIMS

1. A connection system (1) for a multi-bore flying lead or umbilical (2), the connection system comprising a first connector part (3) having a number of couplers (4), a second connector part (5) having a corresponding number of couplers (6), wherein the first connector part (3) is suspended in ends of associated conduits (7), the conduits are extending from one end of the multi-bore flying lead or umbilical (2) into the couplers (4) arranged in the first connector part (3), and wherein the second connector part (5) is mounted stationary in a holding fixture (10), and further wherein in a mating position the first connector part (3) can be pulled towards the second connector part (5) for connection, characterized in
 - that interacting guide means (11; 12) are arranged on the holding fixture (10) and on a bracket (8) that is anchored in said one end (9) of the flying lead or umbilical (2), the interacting guide means comprising an eye (11) on the bracket (8) and a guide post (12) rising from the holding fixture (10), wherein the eye (11) is arranged insertable from above on the guide post (12), to bring the first and second connector parts (3; 5) into mating position through a guided descending motion of the first connector part (3) in relation to the second connector part (5); and
 - that the first connector part (3) is suspended floating in free ends of associated conduits (7), said conduits extending non-constrained from the end (9) of the multi-bore flying lead or umbilical into the bracket (8).
2. The connection system of claim 1, wherein the bracket (8) and the holding fixture (10) are remained in position by the structure weight of the multi-bore flying lead or umbilical (2) as the eye (11) is fully inserted on the guide post (12).
3. The connection system of claim 1 or 2, wherein the guide post (12) rises from a top surface (16) adjoining a front face (14) on the holding fixture (10).

4. The connection system of any previous claim, wherein the guide post (12) comprises a lower end portion (12') with a first radius, and an upper portion (12'') of a second radius, the first radius being larger than the second radius.
- 5 5. The connection system of any previous claim, wherein a guide post extension (17) is insertable over the guide post (12).
6. The connection system of any previous claim, wherein the bracket (8) comprises a distal leg portion (19'; 20') connected pivotally to a proximal leg
10 portion (19''; 20''), the latter fixedly connected to an end fitting (9') of the multi-bore flying lead or umbilical (2).
7. The connection system of any of claims 3-6, wherein the eye (11) is formed in a plate-like bracket member (18) protruding from the distal end of the
15 bracket (8) to be received in overlapping relation with the top surface (16) of the holding fixture (10) in mating position.
8. The connection system of any of previous claim, wherein a lug (21) in a front
20 face (14) of the holding fixture (10) protrudes for engagement with a seat (22) formed in an opposite front face (13) of the bracket (8) in the mating position.

PATENTKRAV

1. Koblingssystem (1) for en flying lead rørbunt eller umbilikal (2), der forbindelsessystemet omfatter en første koblingsdel (3) forsynt med et antall koblinger (4), en andre koblingsdel (5) forsynt med et tilsvarende antall koblinger (6), idet den første koblingsdelen (3) er opphengt i endene av tilknyttede ledninger (7), der ledningene strekker seg fra én ende av flying lead rørbunten eller umbilikalen (2) og til koblingene (4) som er innrettet i den første koblingsdelen (3), og der den andre koblingsdelen (5) er fast montert i en holdeinnretning (10), og videre der i en sammenpasningsposisjon den første koblingsdelen (3) kan skyves inn mot den andre koblingsdelen (5) for tilkobling, karakterisert ved:
- at samvirkende føringsmidler (11; 12) er innrettet på holdeinnretningen (10) og på en brakett (8) som er forankret i nevnte ene ende (9) av flying lead rørbunten eller umbilikalen (2), der de samvirkende føringsmidlene omfatter et øye (11) på braketten (8) og en styrestolpe (12) som reiser seg fra holdeinnretningen (10), idet øyet (11) er innrettet slik at det lar seg sette inn ovenfra på styrestolpen (12) for å bringe første og andre koblingsdel (3; 5) i sammenpasningsposisjon ved hjelp av en styrt nedoverbevegelse av den første koblingsdelen (3) i forhold til den andre koblingsdelen (5), og
 - at den første koblingsdelen (3) er opphengt flytende i frie ender av tilknyttede ledninger (7) og nevnte ledninger strekker seg fritt fra enden (9) av flying lead rørbunten eller umbilikalen og inn i braketten (8).
2. Koblingssystem i henhold til krav 1, idet braketten (8) og holdeinnretningen (10) blir fastholdt i posisjon av vekten av strukturen av flying lead rørbunten eller umbilikalen (2) mens øyet (11) blir helt satt inn på styrestolpen (12).
3. Koblingssystem i henhold til krav 1 eller 2, idet styrestolpen (12) reiser seg fra en toppflate (16) tilgrensende en frontflate (14) av holdeinnretningen (10).
4. Koblingssystem i henhold til hvilket som helst foregående krav, idet styrestolpen (12) omfatter en nedre endedel (12') med en første radius, og en

øvre del (12") med en andre radius, der første radius er større enn den andre radius.

5. Koblingssystem i henhold til hvilket som helst foregående krav, idet en
5 forlengelse av styrestolpen (17) lar seg sette inn på styrestolpen (12).
6. Koblingssystem i henhold til hvilket som helst foregående krav, idet
braketten (8) omfatter en fjerntliggende gren (19'; 20') forbundet dreibart med
en nærliggende gren (19"; 20"), den sistnevnte fast forbundet med en
10 endetilpasning (9') på flying lead rørbunten eller umbilikalen (2).
7. Koblingssystem i henhold til hvilket som helst av kravene 3-6, idet øyet (11)
er utformet som et plateliknende brakettelement (18) som rager frem fra den
fjerne enden av braketten (8) og blir mottatt i overlappende forhold med
15 toppoverflaten (16) på holdeinnretningen (10) i sammenpasningsposisjon.
8. Koblingssystem i henhold til hvilket som helst foregående krav, idet en knast
(21) i en frontflate (14) på holdeinnretning (10) rager ut for å gå i inngrep med
et sete (22) utformet i en motstående frontflate (13) på braketten (8) i
20 sammenpasningsposisjonen.

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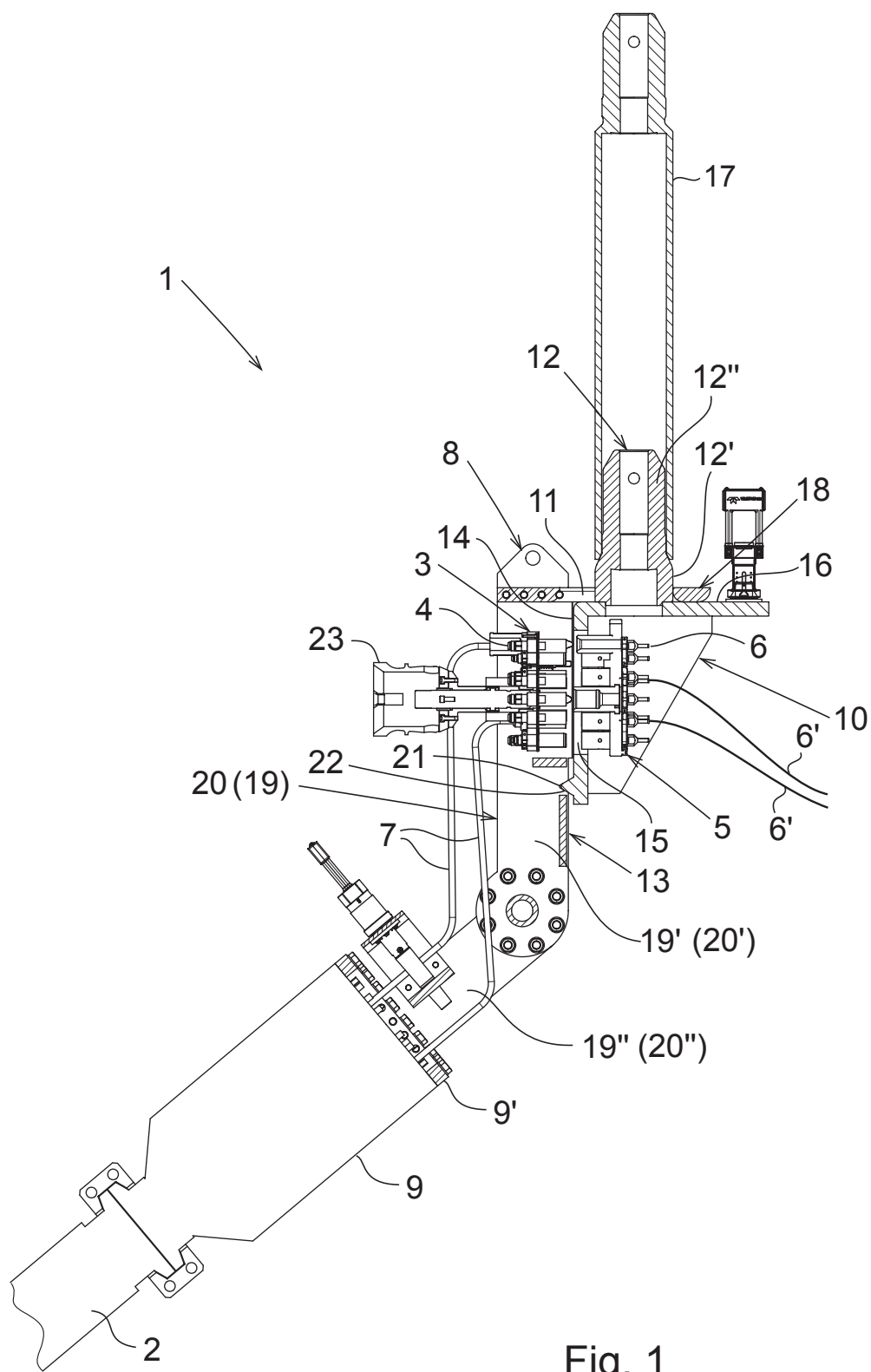


Fig. 1

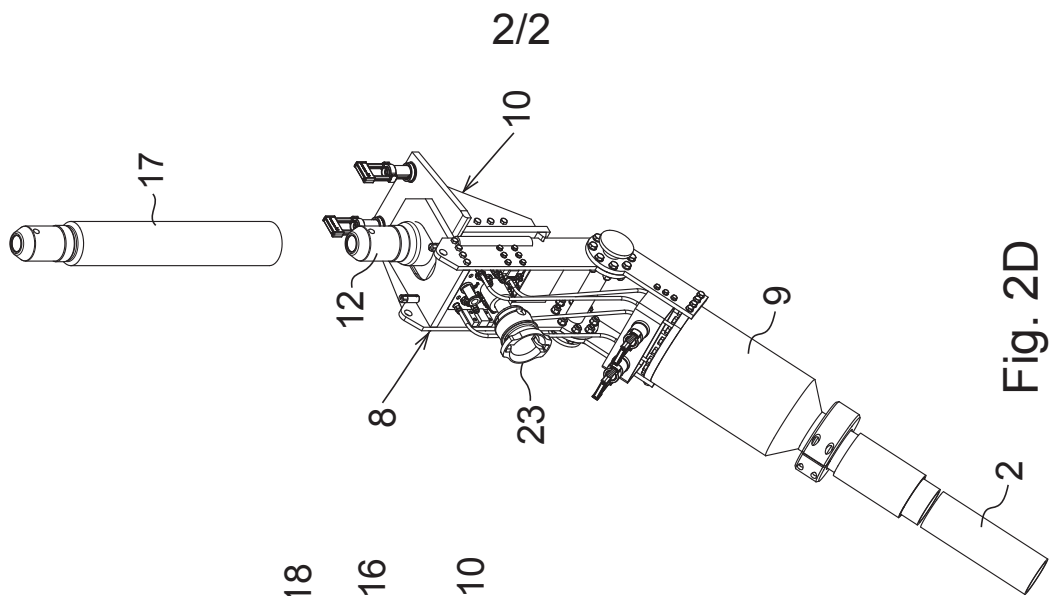


Fig. 2A

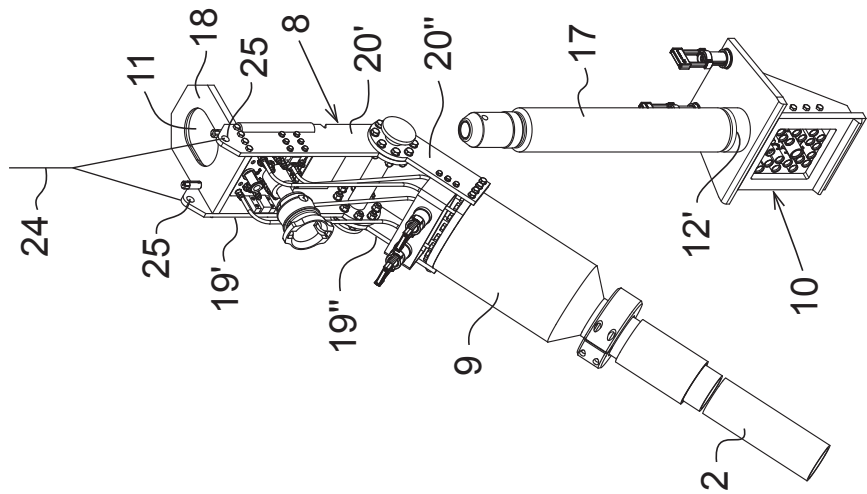


Fig. 2B

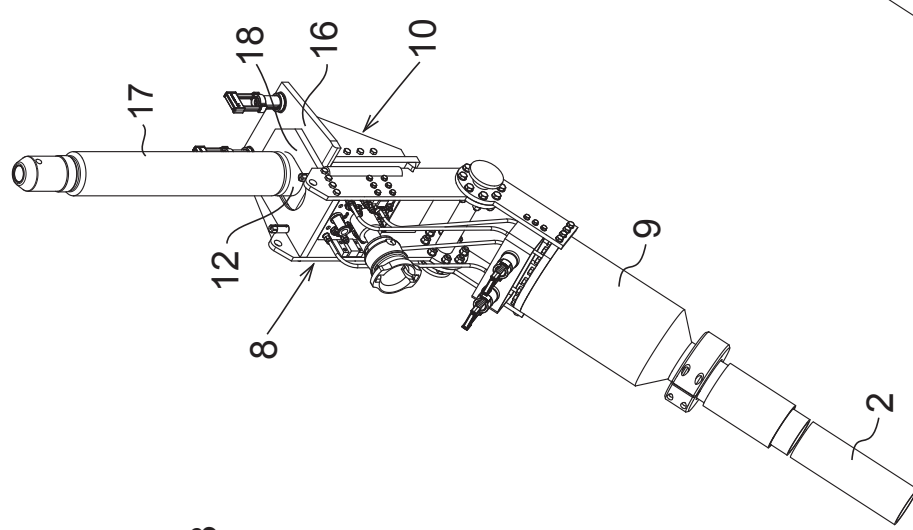


Fig. 2C

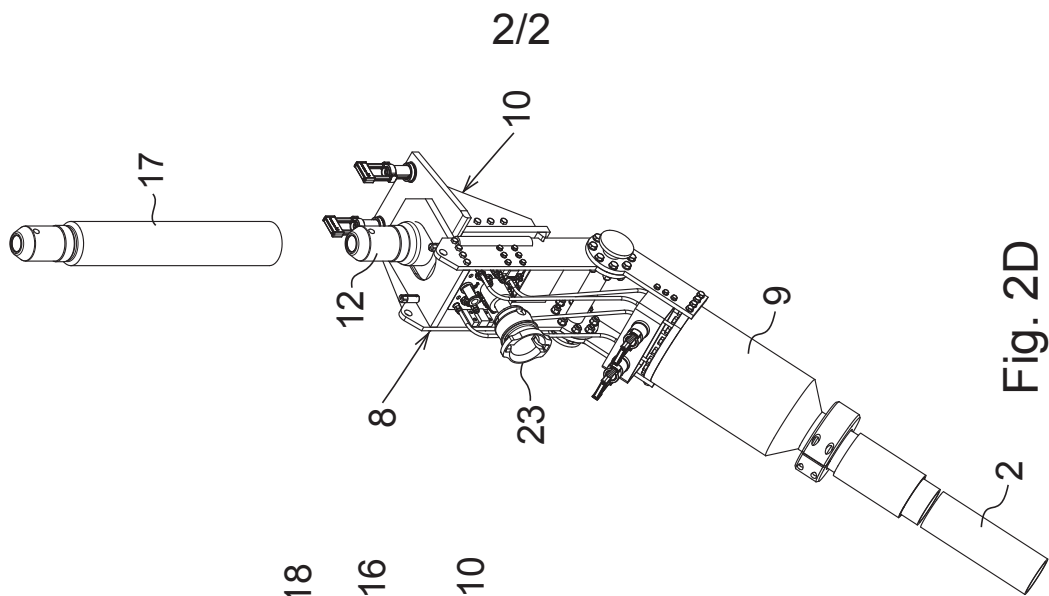


Fig. 2D

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